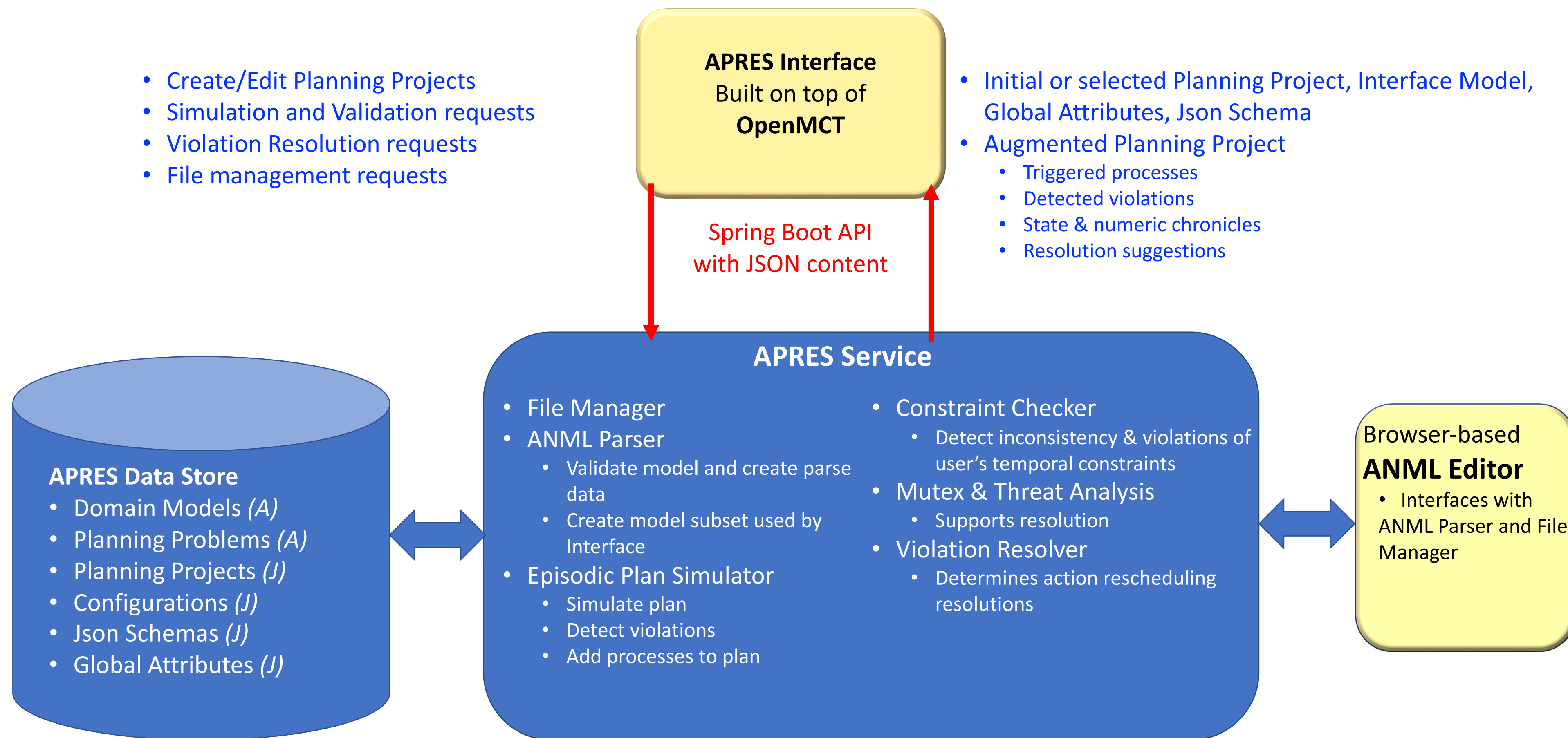


APRES Prototype Mission Planner System Demonstration

John L. Bresina¹, Vijayakumar Baskaran², J Benton³, Hassan Eslami⁴,
Elif Kurklu⁵, David E. Smith⁶, Deep Tailor⁷, and Ramazan Ushpayev⁸
NASA Ames Research Center^{1,3}, KBR Wyle Services, LLC^{2,4,5,7,8}



Interface Layout

Action Dictionary

Action Editor

APRES Service Operations

Action/Process Timelines

Chronicle Timelines

Tables

Unary Constraint Editor

CONSTRAINT EDITOR

DrillStow

Select Timepoint

Select Relation

Input Time: 08-20-2020T12:00:00.000Z

Submit

Constraints Table

Initial Assignments	Violations	Constraints	Resolutions
		Action(s)	Constraint
		Traverse2	Traverse2: end <= 2022-08-13T22:00:00.000Z
		DrillUnStow, DrillAuger	DrillAuger: start - DrillUnStow: end > 00:30:00

Binary Constraint Editor

CONSTRAINT EDITOR

DrillUnStow

Select Timepoint A

DrillAuger

Select Timepoint B

Select Relation

Positive Temporal Distance

Hours: 24

Minutes: 60

Seconds: 60.000

Submit

Violations Table

Initial Assignments	Violations	Constraints	Resolutions
	Time	Type	Violated Object
	2022-08-12T17:37:00.000Z	unsatisfied-condition	auger2:NSS_sys == on
	2022-08-12T20:47:00.000Z	violated-condition	pan1:(DrillArm_sys)==(stowed) or (DrillArm_sys)==(unstowed)
	2022-08-12T23:30:00.000Z	temporal-constraint	pan2:end <= 2022-08-12T18:00:00.000Z

Resolutions Table

Initial Assignments	Violations	Constraints	Resolutions
		Action Name	Original Start
		Traverse2	2022-08-13T22:19:18.000Z
		HazCam_PwrOn2	2022-08-13T22:19:18.000Z
		DrillCam_PwrOn1	2022-08-13T11:24:10.000Z